

150A Homework Solutions

Homework 1

- Section 1.2: 2, 3
- Section 1.3: *8
- Section 1.4: 1b, 2, 10, *11
- Section 1.5: *1, *2, 7, 8, 11

Section 1.2

- Problem 2 α closest to origin means that $\|\alpha\| = \sqrt{\alpha \cdot \alpha}$ is minimal, that is $\alpha \cdot \alpha$ is minimal, therefore $0 = (\alpha \cdot \alpha)' = 2\alpha \cdot \alpha'$ so $\alpha \perp \alpha'$.
- Problem 3 If $\alpha'' = 0$ then by integration $\alpha'(t) = ut + v$ with $u, v \in \mathbb{R}^3$ are constant vectors, so α is a straight line (see do Carmo page 16)

Section 1.3

- Problem 8 See Rudin's "Principles of Mathematical Analysis" pages 136, 137.

Section 1.4

- Problem 1b The basis shown can be obtained by multiplying the standard basis by the matrix $\begin{pmatrix} 1 & 2 & 4 \\ 3 & 3 & 8 \\ 5 & 7 & 3 \end{pmatrix}$ which has determinant +39, so it is positive.

By row reduction:

$$\det \begin{pmatrix} 1 & 2 & 4 \\ 3 & 3 & 8 \\ 5 & 7 & 3 \end{pmatrix} = \det \begin{pmatrix} 1 & 2 & 4 \\ 0 & -3 & -4 \\ 0 & -3 & -17 \end{pmatrix} = \det \begin{pmatrix} 1 & 2 & 4 \\ 0 & -3 & -4 \\ 0 & 0 & -13 \end{pmatrix} = 39$$

- Problem 2 $P = \{(x, y, z): ax + by + cz + d = 0\}$

Assume first that $d = 0$. The position vector (x, y, z) for any point on this plane satisfies $ax + by + cz = 0$. Therefore $(a, b, c) \cdot (x, y, z) = ax + by + cz = 0$ so (a, b, c) is perpendicular to (x, y, z) and therefore to the plane P . Since adding a constant displaces the plane parallel to itself, this still holds for arbitrary d .

Since $v = (a, b, c)$ is perpendicular to P , the distance from the origin to P must be $|rv| = |r||v|$ for some $r \in \mathbb{R}$.

To find r , we must have rv lie in P . That is, $a(ra) + b(rb) + c(rc) + d = 0$ or $v \cdot (rv) = rv \cdot v = -d$ so $r = \frac{-d}{v \cdot v}$. Notice this undefined when $v \cdot v = 0$ which happens when $d = 0$ but then the distance is clearly zero.

$$\text{Therefore distance} = |r||v| = |r|\sqrt{v \cdot v} = \frac{|d|}{v \cdot v} \sqrt{v \cdot v} = \frac{|d|}{\sqrt{v \cdot v}} = \frac{|d|}{\sqrt{a^2 + b^2 + c^2}}$$

Key Point:

- The "distance vector" must be perpendicular to the plane

- Problem 10 Page 13 shows that $\det(S) = A^2$ where $S = \begin{pmatrix} u \cdot u & u \cdot v \\ v \cdot u & v \cdot v \end{pmatrix}$ and A is the area of the parallelogram with edges $u, v \in \mathbb{R}^2$.

Notice that $S = RR^T$ where $R = \begin{pmatrix} u_1 & u_2 \\ v_1 & v_2 \end{pmatrix}$ by the definition of matrix multiplication and dot product. For example, $u \cdot v = (u_1e_1 + u_2e_2) \cdot (v_1e_1 + v_2e_2) = u_1v_1 + u_2v_2$ since $e_1 \cdot e_1 = e_2 \cdot e_2 = 1$ and $e_1 \cdot e_2 = e_2 \cdot e_1 = 0$

Therefore, $A^2 = \det S = \det(RR^T) = (\det R)(\det R^T) = (\det R)(\det R) = \det R^2$ since $\det R = \det R^T$.

- Problem 11

(a) The volume V of a parallelepiped is $V = A \cdot h$ where A is the area of one face and h is the height measured perpendicularly to that face. If u and v define the face, and w is at angle θ with the perpendicular $u \times v$, then $|w| \cos \theta$ gives the height. Since $|u \times v|$ gives the area of the face, we have $\pm V = |u \times v| |w| \cos \theta = (u \times v) \cdot w$ (page 4: $u \cdot v = |u||v| \cos \theta$).

(b) From page 12 we get $\det(u, v, w) = (u \times v) \cdot w$ and arguing as in problem 10 we have $V^2 = \det(R)^2 = \det(RR^T) = \det(S)$ where R is the matrix (u, v, w) and S is as in the exercise.

Section 1.5

- Problem 1 $\alpha(s) = (a \cos \frac{s}{c}, a \sin \frac{s}{c}, b \frac{s}{c})$ with $c^2 = a^2 + b^2$

Note that we need to assume that $a \neq 0$ for most of this problem.

$$\alpha'(s) = \left(-\frac{a}{c} \sin \frac{s}{c}, \frac{a}{c} \cos \frac{s}{c}, \frac{b}{c}\right) \quad \alpha''(s) = \left(-\frac{a}{c^2} \cos \frac{s}{c}, -\frac{a}{c^2} \sin \frac{s}{c}, 0\right)$$

$$(a) \|\alpha'\|^2 = \frac{a^2}{c^2}(\cos^2 \frac{s}{c} + \sin^2 \frac{s}{c}) + \frac{b^2}{c^2} = \frac{a^2}{c^2} + \frac{b^2}{c^2} = 1$$

$$(b) k = |\alpha''| = \sqrt{\frac{a^2}{c^4}} = a/c^2$$

$$b = t \times n = \left(\frac{b}{c} \sin \frac{s}{c}, -\frac{b}{c} \cos \frac{s}{c}, \frac{a}{c}\right)$$

$$b' = \left(\frac{b}{c^2} \cos \frac{s}{c}, \frac{b}{c^2} \sin \frac{s}{c}, 0\right)$$

$$\text{and since } b' = -\frac{b}{c^2} \cdot n = \tau n \text{ we have } \tau = -\frac{b}{c^2}$$

(c) The osculating plane is the plane determined by t and n (or α' and α'' ; and they must be nonzero) at $\alpha(s)$. It is the set of all points p so that $p - \alpha(s)$ is orthogonal to $t \times n$, that is

$$P = \{p \in \mathbb{R}^3: t \times n \perp p - \alpha(s)\} = \{p \in \mathbb{R}^3: t \times n \cdot (p - \alpha(s)) = 0\}.$$

which is the set of all points p so that the $\det(t, n, p - \alpha(s)) = 0$

Since $n = \alpha''/k = (-\cos \frac{s}{c}, -\sin \frac{s}{c}, 0)$ we get

$$x b c \sin \frac{s}{c} - y b c \sin \frac{s}{c} + z a c - a b s = 0$$

or

$$x b \sin \frac{s}{c} - y b \sin \frac{s}{c} + z a - a b \frac{s}{c} = 0$$

(d) We need to show that $(0, 0, 1) \perp n(s)$, that is $(0, 0, 1) \cdot (-\cos \frac{s}{c}, -\sin \frac{s}{c}, 0) = 0$ which is obvious.

(e) We need to show that $(0, 0, 1) \cdot t(s)$ is constant. This is clear both from the expression for t which gives $(0, 0, 1) \cdot t = \frac{b}{c}$ and from the problem above since $(0, 0, 1) \cdot t$ constant means $0 = ((0, 0, 1) \cdot t)' = (0, 0, 1) \cdot t' = k((0, 0, 1) \cdot n)$ since we know $k \neq 0$ (assuming $a \neq 0$)

• Problem 2

$$\begin{aligned}
 \tau &= b' \cdot n && \text{since } b' \cdot n = \tau n \cdot n \\
 &= (t \times n)' \cdot n && \text{since } b = t \times n \\
 &= (t \times n') \cdot n && \text{since } t' \times n = kn \times n = 0 \\
 &= -t \times n \cdot n' && \text{since } u \times v \cdot w = -u \times w \cdot v \\
 &= -\alpha' \times \frac{\alpha''}{k} \cdot \left(\frac{\alpha''}{k}\right)' && \text{since } t = \alpha' \text{ and } n = \alpha''/k \\
 &= -\alpha' \times \frac{\alpha''}{k} \cdot \left(\frac{\alpha''}{k} + \alpha''\left(\frac{1}{k}\right)'\right) \\
 &= -\alpha' \times \frac{\alpha''}{k} \cdot \frac{\alpha'''}{k} && \text{since } = \alpha' \times \frac{\alpha''}{k} \cdot \alpha''\left(\frac{1}{k}\right)' = 0 \\
 &= -\frac{\alpha' \times \alpha'' \cdot \alpha'''}{k^2}
 \end{aligned}$$

Homework 2

- Okikiolu's problem
- Section 2.2: 1, 2, *4, *5, *15

Okikiolu's problem

Show that if a map T from 3-space to itself preserves distance, that is $\forall u, v (|Tu - Tv| = |u - v|)$, then T has the form $Tu = Ou + w$, where w is a 3-vector and O is a linear orthogonal transformation of 3-space.

O is an orthogonal transformation iff $\forall u, v (Ou \cdot Ov = u \cdot v)$.

$$\begin{aligned}
 & (Tu - T0) \cdot (Tv - T0) \\
 &= Tu \cdot Tv - Tu \cdot T0 - Tv \cdot T0 + T0 \cdot T0 \\
 &= \frac{|Tu|^2 + |Tv|^2 - |Tu - Tv|^2}{2} \\
 &\quad + \frac{-|Tu|^2 - |T0|^2 + |Tu - T0|^2}{2} \\
 &\quad + \frac{-|Tv|^2 - |T0|^2 + |Tv - T0|^2}{2} + |T0|^2 \\
 &= -|u - v|^2 + |u|^2 + |v|^2 \\
 &= u \cdot v
 \end{aligned}
 \qquad
 \begin{aligned}
 & \text{Since } a \cdot b = |a|^2 + |b|^2 - |a - b|^2 \\
 & \text{Since, e.g., } |Tu - T0| = |u - 0| = |u| \\
 & \text{Since } a \cdot b = |a|^2 + |b|^2 - |a - b|^2
 \end{aligned}$$

Therefore, we can take $w = T0$ and $Ou = Tu - w$ is orthogonal.

Section 2.2

- Problem 1 Take $\phi(\theta, z) = (\sin \theta, \cos \theta, z)$. Then $\phi'(\theta, z) = \begin{pmatrix} \cos \theta & 0 \\ -\sin \theta & 0 \\ 0 & 1 \end{pmatrix}$.

Its two columns are clearly linearly independent for every θ and z , so ϕ is a coordinate map for every point on the cylinder. ϕ is a smooth with smooth inverses $\phi^{-1}(x, y, z) = (\arctan(x/y), z) + k\pi$ ($k \in \mathbb{Z}$) (these are compositions of known smooth functions).

- Problem 2 The first set is not a regular surface since the points with $x^2 + y^2 = 1$ (i.e., on the boundary) fail point 2 of the definition. The second set is a regular surface: the coordinate map $\phi(x, y) = (x, y, 0)$ is clearly smooth with smooth

$$\text{inverse and } \phi'(x, y) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix}.$$

- Problem 3 The two-sheeted cone has a singularity at $(0,0,0)$. This is not so easy to prove. Consider any neighborhood U induced on it by a neighborhood of \mathbb{R}^3 . If we remove the point $(0,0,0)$ from this neighborhood, we get two disconnected sets. However, any neighborhood V of \mathbb{R}^2 with one point removed is connected, hence no such V can be homeomorphic to U and we fail condition 2 of the definition.
- Problem 4 $f(x, y, z) = z^2$ so $f'(x, y, z) = (0, 0, 2z)$. Notice that $(0, 0, 0) \in f^{-1}[\{0\}] = \mathbb{R}^2$ and $(0,0,0)$ is a singular point since $f'(0, 0, 0) = (0, 0, 0)$. Hence 0 is not a regular value of f . But clearly \mathbb{R}^2 is a regular surface.

- Problem 5 The function given (I'll call it ϕ since I don't like \mathbf{x}) $\phi(u, v) = (u + v, u + v, uv)$ is a parametrization of P , since it is smooth (composition of smooth functions) with smooth inverse (by prop. 2.2.4 since $P \approx \mathbb{R}^2$ is regular) $\phi^{-1}(x, y, z) = \left(\frac{x + \sqrt{x^2 - 4z}}{2}, \frac{x - \sqrt{x^2 - 4z}}{2}\right)$ (we get this from solving the equations: $x = u + v$ and $z = uv$ and by choosing the signs to satisfy $u > v$). We have

$$\phi'(u, v) = \begin{pmatrix} 1 & 1 \\ 1 & 1 \\ v & u \end{pmatrix} \text{ which has rank two since } u > v, \text{ so } \phi \text{ is regular. Finally}$$

since $\{(u, v) \in \mathbb{R}^2: u > v\}$ is homeomorphic to \mathbb{R}^2 , ϕ is a parameterization of P .

- Problem 15 For a given t , the equation of the line going from $(0, 0, t)$ to $(a, t, 0)$ can be given by $(sa, st, (1-s)t)$ so the set of points formed by these lines is $\phi[\mathbb{R}^2]$ where $\phi: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ is given by $\phi(s, t) = (sa, st, (1-s)t)$. ϕ is clearly a local

$$\text{homeomorphism and } \phi'(s, t) = \begin{pmatrix} a & 0 \\ t & s \\ -t & 1-s \end{pmatrix} \text{ is regular since } a \neq 0.$$

Therefore, the surface so defined is regular.

Homework 3

- Section 2.3: 1, 2, 3, 4, 5
- Problem 1 Clearly A is a smooth bijection, it maps the sphere onto the sphere, and it is its own inverse.
- Problem 2 π is smooth by the comments in example 1 on page 72, since $\pi \subseteq \pi'$ where π' is the projection from \mathbb{R}^3 onto \mathbb{R}^2 .
- Problem 3 Take $\phi(x, y) = (x, y, x^2 + y^2)$. Clearly, ϕ is smooth (it is a parametrization of the paraboloid, by definition) and its inverse is the projection which we saw above is smooth too.
- Problem 4 $\phi(x, y, z) = (ax, by, cz)$ maps the sphere into the ellipsoid smoothly and injectively with inverse $\phi(x, y, z) = (x/a, y/b, z/c)$. (We can assume $a, b, c \neq 0$ from the statement of the problem.)
- Problem 5 $d(p) = |p - p_0|$ is clearly smooth from \mathbb{R}^3 to \mathbb{R} except at $p = p_0$. Since $p_0 \notin S$, $d(p)$ is smooth from S to \mathbb{R} by the comments in example 1 on page 72.

Homework 4

- Section 2.4: 1, 2, 3, 12

When a surface is given by $f^{-1}[\{a\}]$ for a regular value a of some smooth function $f: \mathbb{R}^3 \rightarrow \mathbb{R}$, we have that for any curve α on that surface, $f(\alpha(t)) = a$ and therefore $df \circ d\alpha = 0$. If we choose an orthonormal basis, then df and $d\alpha$ are given, respectively, by a row and a column vector and $Df \cdot D\alpha = 0$ where the multiplication is just matrix multiplication. This is the same as saying $(Df)^T \cdot D\alpha = (\partial f/\partial x, \partial f/\partial y, \partial f/\partial z) \cdot d\alpha/dt = 0$ (dot product). Therefore, any tangent vector is orthogonal to $(Df)^T$ so $(Df)^T$ is a vector normal to the tangent plane. We will use this for several of the problems (where Df stands for the matrix of the differential in the standard basis of \mathbb{R}^n).

- Problem 1 From above, the equation of the plane at $p_0 = (x_0, y_0, z_0)$ is just $(Df)^T \cdot (p - p_0) = 0$ since $(Df)^T$ is normal to the tangent plane at p_0

Writing it out in more detail we have:

$$\frac{\partial f}{\partial x}(x_0, y_0, z_0)(x - x_0) + \frac{\partial f}{\partial y}(x_0, y_0, z_0)(y - y_0) + \frac{\partial f}{\partial z}(x_0, y_0, z_0)(z - z_0) = 0$$

- Problem 2 Take $f = x^2 + y^2 - z^2$. The normal to the plane tangent to $f^{-1}[\{1\}]$ (our surface) at (x, y, z) is $(Df)^T = (2x, 2y, -2z)$. At any point with $z = 0$ this is $(2x, 2y, 0)$ which is orthogonal to $(0, 0, 1)$ (the z-axis). Since the normal of the tangent plane is orthogonal to the z-axis, the tangent plane is parallel to it.
- Problem 3 We can do this two ways.

(a) Define $g(x, y, z) = z - f(x, y)$. By problem 1, the tangent plane at (x_0, y_0, z_0) is:

$$-\frac{\partial f}{\partial x}(x_0, y_0, z_0)(x - x_0) - \frac{\partial f}{\partial y}(x_0, y_0, z_0)(y - y_0) + 1(z - z_0) = 0$$

Since $z_0 = f(x_0, y_0)$, we get:

$$\frac{\partial f}{\partial x}(x_0, y_0, z_0)(x - x_0) + \frac{\partial f}{\partial y}(x_0, y_0, z_0)(y - y_0) + f(x_0, y_0) = z$$

(b) Use $\phi(x, y) = (x, y, f(x, y))$, which is a parametrization since it is smooth and

$D\phi = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ \partial f/\partial x & \partial f/\partial y \end{pmatrix}$ always has rank 2. Two basis vectors for the tangent

space are $D\phi \cdot \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ \partial f/\partial x \end{pmatrix} = u$ and $D\phi \cdot \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ \partial f/\partial y \end{pmatrix} = v$, so a

normal vector to the tangent space (and therefore also to the tangent plane) is

$$n = u \times v = \begin{pmatrix} -\partial f/\partial x \\ -\partial f/\partial y \\ 1 \end{pmatrix}.$$

Now that we have a normal vector, we proceed as in part (a).

- Problem 12 Define the functions $f(x, y, z) = x^2 + y^2 + z^2 - ax$, $g(x, y, z) = x^2 + y^2 + z^2 - by$, and $h(x, y, z) = x^2 + y^2 + z^2 - cz$.

Then our three surfaces are $R = f^{-1}[\{0\}]$, $S = g^{-1}[\{0\}]$, and $T = h^{-1}[\{0\}]$.

The corresponding derivatives are: $Df = (2x - a, 2y, 2z)$, $Dg = (2x, 2y - b, 2z)$, and $Dh = (2x, 2y, 2z - c)$. These can only be zero at $(a/2, 0, 0)$, $(0, b/2, 0)$, and $(0, 0, c/2)$ respectively, but these three points are not on the respective surfaces (i.e. $f(a/2, 0, 0) = a^2/4 - a^2/2 \neq 0$ since we are given $a \neq 0$ and similarly for the other two). The functions are clearly smooth and so by 2.2.2, R, S, T are regular surfaces. The normals to their tangent planes are given by the transposes of these derivatives as we saw above.

On $R \cap S = \{(x, y, z) : f(x, y, z) = g(x, y, z) = 0\}$ we have

$$(Df)^T \cdot (Dg)^T = (2x - a)2x + 2y(2y - b) + 4z^2 = 4x^2 + 4y^2 + 4z^2 - 2ax - 2by = 2f(x, y, z) + 2g(x, y, z) = 0$$

since on $R \cap S$ we have $f(x, y, z) = g(x, y, z) = 0$.

Since their normals are orthogonal, the tangent planes of R and S intersect orthogonally, and that means that the surfaces R and S intersect orthogonally.

The same argument works for $R \cap T$ and $S \cap T$.

Homework 5

- Section 2.5: 1a, 1c, 2, 4, 7, 11
- Problem 1a First fund. form for $x(u, v) = (a \sin u \cos v, b \sin u \sin v, c \cos u)$

$$Dx = \begin{pmatrix} a \cos u \cos v & -a \sin u \sin v \\ b \cos u \sin v & b \sin u \cos v \\ -c \sin u & 0 \end{pmatrix}$$

$$\text{Define } r = Dx \begin{pmatrix} 1 \\ 0 \end{pmatrix} \text{ and } s = Dx \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

Then the first fundamental form is given by the matrix

$$\begin{pmatrix} \langle r, r \rangle & \langle r, s \rangle \\ \langle s, r \rangle & \langle s, s \rangle \end{pmatrix} = \begin{pmatrix} E & F \\ F & G \end{pmatrix} \text{ where}$$

$$E = a^2 \cos^2 u \cos^2 v + b^2 \cos^2 u \sin^2 v + c^2 \sin^2 u$$

$$F = (b^2 - a^2) \sin u \cos u \sin v \cos v$$

$$G = a^2 \sin^2 u \sin^2 v + b^2 \sin^2 u \cos^2 v$$

- Problem 1c First fund. form for $x(u, v) = (au \cosh v, bu \sinh v, u^2)$

$$Dx = \begin{pmatrix} a \cosh v & au \sinh v \\ b \sinh v & bu \cosh v \\ 2u & 0 \end{pmatrix}$$

$$E = a^2 \cosh^2 v + b^2 \sinh^2 v + 4u^2$$

$$F = (a^2 + b^2)u \cosh v \sinh v$$

$$G = a^2 u^2 \sinh^2 v + b^2 u^2 \cosh^2 v$$

- Problem 2 Find $\cos \beta$ where β is the acute angle of a curve with range $P \cap S^2$ and the semimeridian $\phi = \phi_0$ where S^2 is parametrized by $r(\phi, \theta) = (\sin \theta \cos \phi, \sin \theta \sin \phi, \cos \theta)$ and $P = \{(x, y, z) \in \mathbb{R}^3: x = kz\}$ where $k = \cotan \alpha$.

Using the parametrization we have:

$$P \cap S^2 = P \cap \text{Rr} = \{(\sin \theta \cos \phi, \sin \theta \sin \phi, \cos \theta): \sin \theta \cos \phi = k \cos \theta\} = \{(\sin \theta \cos \phi, \sin \theta \sin \phi, \cos \theta): \cos \phi = k \cotan \theta\}$$

So we want a curve with $\phi = \arccos(k \cotan \theta)$, for example,

$$\alpha(\theta) = (\arccos(k \cotan \theta), \theta)$$

$$\text{with tangent vector } \alpha'(\theta) = \left(\frac{k}{\sin^2 \theta \sqrt{1 - k^2 \cotan^2 \theta}}, 1 \right) = \left(\frac{1}{\sin \theta \sqrt{k^2 \sin^2 \theta - \cos^2 \theta}}, 1 \right)$$

A semimeridian curve is given by $\beta(\theta) = (\phi_0, \theta)$ with tangent $\beta'(\theta) = (0, 1)$.

$$\text{Where they intersect we have } \beta = \frac{\langle \alpha', \beta' \rangle}{|\alpha'| |\beta'|}$$

where the inner product is given by the first fundamental form.

$$Dr = \begin{pmatrix} -\sin \theta \sin \phi & \cos \theta \cos \phi \\ \sin \theta \cos \phi & \cos \theta \sin \phi \\ 0 & -\sin \theta \end{pmatrix}$$

so

$$E = \sin^2 \theta \sin^2 \phi + \sin^2 \theta + \cos^2 \phi = \sin^2 \theta$$

$$F = -\sin \theta \cos \theta \sin \phi \cos \phi + \sin \theta \cos \theta \sin \phi \cos \phi = 0$$

$$G = \cos^2 \theta \cos^2 \phi + \cos^2 \theta \sin^2 \phi + \sin^2 \theta = 1$$

Since $F = 0$ the calculations are easy. We get $\langle \beta', \beta' \rangle = 1$ and $\langle \alpha', \beta' \rangle = 1$.

$$\langle \alpha', \alpha' \rangle = \sin^2 \theta \frac{1}{(\sin \theta \sqrt{k^2 \sin^2 \theta - \cos^2 \theta})^2} + 1 = \frac{1}{k^2 \sin^2 \theta - \cos^2 \theta}$$

$$\text{and so } \beta = \frac{\langle \alpha', \beta' \rangle}{|\alpha'| |\beta'|} = \sqrt{k^2 \sin^2 \theta - \cos^2 \theta}$$

Since the intersection will happen when $\arccos(k \cotan \theta) = \phi_0$ we need to have $\cotan \theta = \frac{1}{k} \cos \phi_0$ so $\theta = \arctan \frac{k}{\cos \phi_0}$

$$\text{Plugging this into what we got above, we get } \cos \beta = \sqrt{\frac{1+k^2/\cos^2 \phi_0}{1+k^4/\cos^2 \phi_0}}$$

(The “acute angle” part tells us to select the positive square root.)

- Problem 4 Given a surface parametrized by

$$x(u, v) = (u \cos v, u \sin v, \log \cos v + u) \quad (\text{for } -\pi/2 < v < \pi/2)$$

show that the two curves $x(u_1, \bullet)$ and $x(u_2, \bullet)$ determine arcs of equal length on all curves $x(\bullet, v_0)$

$$Dx = \begin{pmatrix} \cos v & -u \sin v \\ \sin v & u \cos v \\ 1 & -\tan v \end{pmatrix}$$

so

$$E = \cos^2 v + \sin^2 v + 1 = 2$$

$$F = -u \cos v \sin v + u \cos v \sin v - \tan v = -\tan v$$

$$G = u^2 \sin^2 v + u^2 \cos^2 v + \tan^2 v = u^2 + \tan^2 v$$

The length of the curve α where $\alpha(u) = x(u, v_0)$ between u_1 and u_2 is given by:

$$\int_{u_1}^{u_2} \sqrt{E \frac{\partial u}{\partial u}} du = \int_{u_1}^{u_2} \sqrt{2} du = \sqrt{2}(u_2 - u_1) \quad \text{since } \frac{\partial v_0}{\partial u} = 0.$$

Clearly this value does not depend on v_0 , which is what we need to show.

- Problem 7 Show that the curves of a parametrization x are a Tchebyshef net iff $\frac{\partial E}{\partial v} = \frac{\partial G}{\partial u} = 0$

The length of any two curves $x(\bullet, v_1)$ and $x(\bullet, v_2)$ between u_1 and u_2 are given by

$$\int_{u_1}^{u_2} \sqrt{E(u, v_1) \frac{\partial u}{\partial u}} du = \int_{u_1}^{u_2} \sqrt{E(u, v_1)} du$$

$$\int_{u_1}^{u_2} \sqrt{E(u, v_2) \frac{\partial u}{\partial u}} du = \int_{u_1}^{u_2} \sqrt{E(u, v_2)} du$$

But since $\frac{\partial E}{\partial v} = 0$ we must have $E(u, v_1) = E(u, v_2)$ so these two lengths are equal. A similar argument shows that the length of any two curves $x(u_1, \bullet)$ and $x(u_2, \bullet)$ between v_1 and v_2 is equal when $\frac{\partial G}{\partial u} = 0$.

Now assume $\frac{\partial E}{\partial v}(u_0, v_1) \neq 0$ for some u_0, v_1 . Since E is smooth, there must be some v_2 so $E(u, v_1) \neq E(u, v_2)$. Assume $E(u, v_1) < E(u, v_2)$. Then since E is smooth, we must have u_1, u_2 with $u_1 < u_0 < u_2$ so that $E(u, v_1) < E(u, v_2)$ for all $u \in [u_1, u_2]$. Therefore, the length of the curve $x(\bullet, v_1)$ must be less than the length of the curve $x(\bullet, v_2)$ between u_1 and u_2 . If instead, $E(u, v_2) < E(u, v_1)$ we get the opposite inequality. Either way, the curves of the parametrization are not a Tchebysef net. A similar argument shows that if $\frac{\partial G}{\partial u}(u_1, v_0) \neq 0$ for some u_1, v_0 , then the curves of the parametrization are not a Tchebysef net.

Homework 7

- Section 3.3: 1, 5, 13, 14, 15, 21.
- Problem 1 At $(0, 0, 0)$ the hyperboloid $z = axy$ we have $K = -a^2$ and $H = 0$
Take the parametrization $\phi(x, y) = (x, y, axy)$.

$$\text{Then } D\phi = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ ay & ax \end{pmatrix} \text{ and since } z - axy = 0, N = \frac{1}{\sqrt{1+a^2x^2+a^2y^2}} \begin{pmatrix} -ay \\ -ax \\ 1 \end{pmatrix}.$$

From $D\phi$ we get $E = 1 + a^2y^2$, $F = a^2xy$ and $G = 1 + a^2x^2$.

We have $\partial_x\phi = (1, 0, ay)$ and $\partial_y\phi = (1, 0, ax)$ so

Then $e = \langle N, \partial_x\partial_x\phi \rangle = 0$ since $\partial_x\partial_x\phi = 0$

and $g = \langle N, \partial_y\partial_y\phi \rangle = 0$ since $\partial_y\partial_y\phi = 0$

$$\text{and } f = \langle N, \partial_x\partial_y\phi \rangle = \frac{1}{\sqrt{1+a^2x^2+a^2y^2}} \left\langle \begin{pmatrix} -ay \\ -ax \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ a \end{pmatrix} \right\rangle = \frac{a}{\sqrt{1+a^2x^2+a^2y^2}}.$$

Also, $EG - F^2 = 1 + a^2y^2 + a^2x^2 + a^4x^2y^2 - a^4x^2y^2 = 1 + a^2y^2 + a^2x^2$

Therefore, $K = \frac{eg - f^2}{EG - F^2} = -\frac{f^2}{EG - F^2}$ which at $(0, 0, 0)$ is $-a^2$.

$$\text{Now } a_{11} = \frac{fF - eG}{EG - F^2} = \frac{fF}{EG - F^2}$$

$$\text{and } a_{22} = \frac{fF - gE}{EG - F^2} = \frac{fF}{EG - F^2}$$

Both of these are zero at $(0, 0, 0)$ so $H = \frac{1}{2}(a_{11} + a_{22}) = 0$.

- Problem 5 For $x(u, v) = (u - u^3/3 + uv^2, v - v^3/3 + vu^2, u^2 - v^2)$

(a) $E = G = (1 + u^2 + v^2)^2$ and $F = 0$

We have $Dx = \begin{pmatrix} 1 - u^2 + v^2 & 2uv \\ 2uv & 1 + u^2 - v^2 \\ 2u & -2v \end{pmatrix}$

so $E = (1 - u^2 + v^2)^2 - 4u^2v^2 - 4u^2 = (1 + u^2 + v^2)^2$

and $G = (1 + u^2 - v^2)^2 - 4u^2v^2 - 4v^2 = (1 + u^2 + v^2)^2$

and $F = 2uv((1 - u^2 + v^2) + (1 + u^2 - v^2)) - 4uv = 4uv - 4uv = 0$

(b) $e = 2, g = -2$ and $f = 0$

The normal is $N = \frac{1}{1+u^2+v^2}(-2u, 2v, 1 - u^2 - v^2)$

and $\partial_u x = (1 - u^2 + v^2, 2uv, 2u)$ and $\partial_v x = (2uv, 1 + u^2 - v^2, -2v)$

so $e = \langle N, \partial_u \partial_u x \rangle = \frac{1}{1+u^2+v^2} \left\langle \begin{pmatrix} -2u \\ 2v \\ 1 - u^2 - v^2 \end{pmatrix}, \begin{pmatrix} -2u \\ 2v \\ 2 \end{pmatrix} \right\rangle = \frac{2+2u^2+2v^2}{1+u^2+v^2} = 2$

and $g = \langle N, \partial_v \partial_v x \rangle = \frac{1}{1+u^2+v^2} \left\langle \begin{pmatrix} -2u \\ 2v \\ 1 - u^2 - v^2 \end{pmatrix}, \begin{pmatrix} 2u \\ -2v \\ -2 \end{pmatrix} \right\rangle = -\frac{2+2u^2+2v^2}{1+u^2+v^2} = -2$

and $f = \langle N, \partial_u \partial_v x \rangle = \frac{1}{1+u^2+v^2} \left\langle \begin{pmatrix} -2u \\ 2v \\ 1 - u^2 - v^2 \end{pmatrix}, \begin{pmatrix} 2v \\ 2u \\ 0 \end{pmatrix} \right\rangle = 0.$

(c) $k_1 = \frac{2}{(1+u^2+v^2)^2}$ and $k_2 = -\frac{2}{(1+u^2+v^2)^2}$

Here compute $a_{11}, a_{12}, a_{21}, a_{22}$, notice that $a_{12} = a_{21} = 0$ and $a_{11} < a_{22}$ so $k_1 = a_{22}$ and $k_2 = a_{11}$

Or, use $k_1 = e/E$ and $k_2 = g/G$ since $F = f = 0$ (see page 162).

(d) The lines of curvature are the coordinate curves

This follows from the fact that $F = f = 0$ by the comments on page 161.

From page 160, a curve α is asymptotic iff $II(\alpha') = 0$